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Nb₃Sn Cos(θ) Dipole Mirror Magnet, HFDM-05 Production Report

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8.0 Summary

1.0 INTRODUCTION

HFDM-05 is the sixth Nb_3Sn cosine theta dipole mirror magnet to be fabricated at Fermilab. 5 dipole magnets of this style were also built and tested. Table 1.0.1 lists the previous models in the HFDA series and the numbers assigned to the production reports that describe them.

 Table 1.0.1
 HFDA Model Magnet Production Report Numbers

Model number	Fabrication Report Number
HFDA01 dipole	TD-00-069
HFDA02 dipole	TD-01-036
HFDA03 dipole	TD-01-064
HFDA04 dipole	TD-02-025
HFDA03A mirror	TD-03-001
HFDA03B mirror	TD-03-030
HFDM02 mirror	TD-03-029
HFDM03 mirror	TD-05-006
HFDA05 dipole	TD-04-048
HFDM04 mirror	TD-05-023

The primary features of HFDM05 are listed below in Table 1.0.2. The magnet cross-section is shown in Figure 1.0.1.

Table 1.0.2 Primary Features of HFDM05

Inner/Outer Cable Strand Type	RRP		
Inner/Outer Cable Strand No.	39		
Strand Diameter	.7mm		
Strand Manufacturer	Oxford Industries		
Cable lay direction	Left Lay		
Cable Cleaning Fluid	ABZOL VG		
Inner and Outer Cable Insulation	125uM x 12mm wide dry ceramic tape wrapped with 30% overlap. Before curing, CTD-1008 binder is painted onto coil.		
Bore Diameter	43.5 mm		
Coil curing temp.	150C		
Inter-layer insulation	3 layers of 125 micron thick ceramic sheet		
Ground Wrap	3 layers of 125 micron thick ceramic sheet		
Strip Heater design	Hand made assembly, with (2) 25 micron thick x 9.5 mm wide stainless strips per quadrant bonded to a 75 micron kapton sheet. See section 4.3. Strip was placed between coil and 1 st ground wrap layer, with kapton toward coil.		
Coil Reaction Cycle	See section 4.1.		
Voltage Tap Plan	See Section 4.3		
Impregnation cycle	CTD101K epoxy, evacuated to 20-40 microns, heated to 60C, .04cc/sec flow rate, cure for 21 hours at 125C. See section 5.1		

Strain Gauges	Resistive gauges on spacers, both in straight section and at lead end. Capacitive gauges at upper and lower outer
	pole, in straight section.
Spot Heaters	None.
Spacer Style	Aluminum Bronze half round.
Mechanical shim system	See sections 6.1 and 6.3.
End longitudinal loading	None.
Strain Gauges on Skin	Yes. See section 7.1.
Other	
Coil Fabrication Start Date	2/2/05
Cold Mass Completion Date	4/20/05

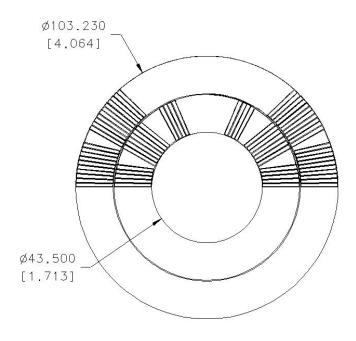


Figure 1.0.1 HFDM05 cross section

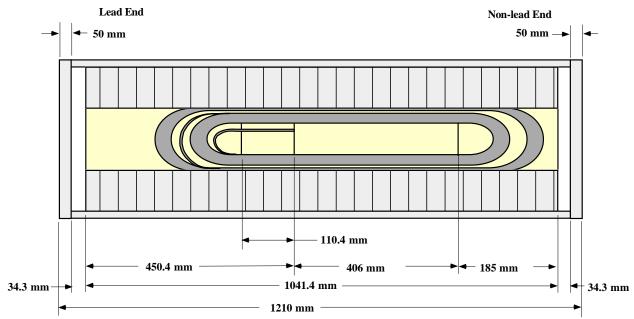


Figure 1.0.2: Longitudinal parameters of HFDM-05

Fig. 1.0.3 shows the magnet nearing completion.



Fig. 1.0.3 *Photograph of HFDM-05.*

Some important features of HFDM-05:

- As in HFDM04, strand is .7mm RRP made by Oxford Industries.
- As in HFDM04, cable and magnet cross section were changed from HFDA05, due to the change in strand diameter.
- Original design of cable for HFDM04 and HFDM05 included a keystone angle of 1.3 degrees, with midthickness of 1.240 mm. All coil parts (end and straight section) were designed for cable of this cross section. This specification was subsequently changed, and the actual cable used had a keystone angle of .972 degrees, with a midthickness of 1.258 mm. See section 3.1 for more details.

2.0 STRAND and CABLE

Strand for HFDM05 was made by Oxford Industries using the RRP Process. Billets numbers were 7054, 7060 and 6813. The nominal diameter of the strand was .7 mm. Strand parameters are described in table 2.0.1.

Table 2.0.1: Strand Description

Table 2.0.1. Strand Description.				
Billet ID	7054,7060,6813			
Strand diameter, mm	0.7			
$I_{c}(12 \text{ T}), A$	~500			
Cu fr., %	50			
No. of filaments	54/61			
D _{eff} , μm	85			
Geometric filament size, µm	61-75			
RRR	40			
No. units	20			
Total length, m	12,000			
Average length/unit, m	600			
Twist pitch, mm	12			

2.1 Cable Mechanical Parameters

Rutherford type cable with 39 strands was manufactured to a rectangular cross section at LBL, then annealed and re-rolled to the keystone angle at FNAL. Cable reel number was F5O-B00911. Cable mechanical parameters are listed in Table 2.1.1.Cable used in HFDM05 did not include a stainless steel core.

Table 2.1.1 :	Cable	parameters.
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Parameter	Unit	Design Value	Measured Value (rectangular)	Final Measured Value
Strand Diameter	mm	.7 mm	.7029 mm	.7029 mm
Mid-Thickness	mm	1.2 mm*	1.351 mm	1.258 mm*
Width	mm	14.34 +/025 mm	13.921 mm	14.24 mm
Keystone angle	deg	0.95 deg	-0.072 deg	.972 deg
Pitch Length	mm	111 mm	109	109
Number of Strands		39	39	39
Lay Direction		left	left	left
Packing Factor	%	87.2		
Reel Number		F5O-B00911		

^{*} Design value assumes applied pressure of 35 MPa. Measurements were taken at 15MPa.

2.2 Cable Electrical Parameters

During magnet fabrication, both virgin (round) and extracted strand samples were placed as witness samples, first in the oven when the cable was pre-annealed, then on the reaction fixture inside the retort, along with the coil assembly, during the reaction cycle (see section 4.1 for reaction cycle details).

Electrical tests were performed on the witness sample strands after reaction of the coils. Table 2.2.1 and Figure 2.2.1 show measurements made on these samples at SSTF for the coil used in HFDM05 (HFDDH-002). Table 2.2.2 shows magnet quench currents at 4.5 and 2.2K. Figure 2.2.2 and Table 2.2.3 show self-field test results at 4.2 K for impregnated and non-impregnated keystoned RRP cables used as witnesses of the half-coil HFDDH02 (911's) used in HFDM05. Results for the coil used in the previous mirror HFDM04 (HFDDH01) (891's) are also shown.

Table 2.2.1: *Measured critical parameters of the witness samples of coil HFDDH-002*.

Strand ID	I _c (A),n at 15 T	14 T	13 T	12 T	10 T	8 T	6 T	Bar rel	Pro be	$I_s(A),B_s(T)$	RRR
HFDDH02		Actu	al HT w	as 100 h	at 210°0	C, 48 h at	400°C,	50 h	at 6	650°C	
VG. 7054	Q 219			Q 297	Q 404			Ti	2	100,2.32	64
VG. 7060	Q 209	Q 254		Q 362	Q 497			Ti	2?	425,2.0	36
VG. 6813	Q 203	Q 252		Q 374	Q 514			Ti	2	750,1.0	80
VG. 7054	177,38	228,42	(289)	360,44	Q 520	Q 625	Q 625	SS	1	590,1.04	274
Extr. #1	167,24	211,23	261,23	325	Q 416	Q 519	Q 570	Ti	1	325,1.02	64
Extr. #2	185,30	242,22	Q 294	Q 352	Q 449	Q 550	Q 555	Ti	2	487,1.02	68
Extr. #3*	Q 96			Q 123				SS	2		35

Some resistivity observe

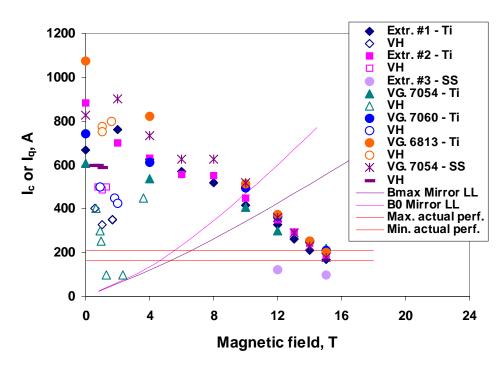


Figure 2.2.1: I_c or I_q as obtained through VI and VH measurement as a function of magnetic field for 0.7 mm 54/61 RRP strands extracted from cable 911 and used as witnesses of half-coil HFDDH02. The red line shows actual performance of HFDDH02.

Table 2.2.2 Magnet Quench Currents at 4.5 K and 2.2 K

	THE EVENT MATERIAL CONTRACTOR TO THE PROPERTY OF THE PROPERTY						
	Meas. I _{min} (4.5 K)-I _{max} (4.5 K), A	Meas. I _{min} (2.2 K)-I _{max} (2.2 K), A					
HFDM05 (HFDDH02)	6330-8187	8397					

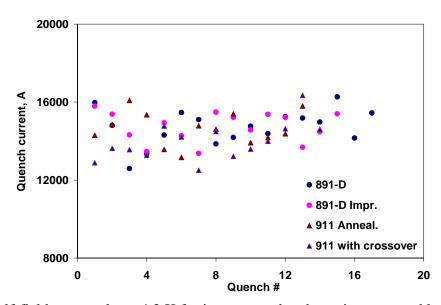


Fig. 2.2.2: Self-field test results at 4.2 K for impregnated and non-impregnated keystoned RRP cables used as witnesses of half-coils HFDDH01 (891-D's) and HFDDH02 (911's)

Table. 2.2.3: Witness Cable Test Results for HFDM04 and HFDM05

HEAT TREATMENT	Cable ID	Impregn	Cable	Cable	Min. I _q /strand,
IILAI IKLAIMENI	Cable ID	ation	Ave. I _q , A	Min. I _q , A	A
HFDDH01	891-D	N	14710	12588	322
"	44	Y	14731	13375	343
HFDDH02	911	N	14644	13166	337
	46	N	13978	12500	320

Figure 2.2.3 shows the predicted short sample limits for coil HFDDH-002.

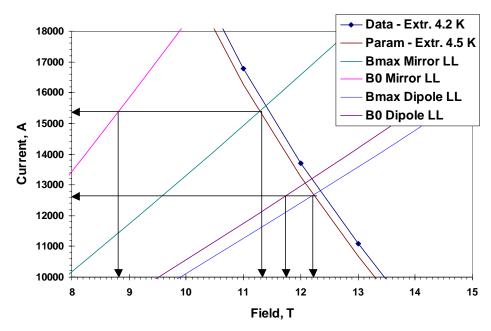


Fig. 2.2.3: High field short sample limit for half-coil HFDDH020in a mirror and dipole configurations.

Table 2.2.4 shows the mirror maximum quench currents with SSL predictions for HFDM05 and the previous mirror HFDM04.

Table 2.2.4 Comparison of Mirror Maximum Quench Currents with Various SSL Predictions

		Meas.	Meas. Min. Iq	Calc. (strand)
	T0, K	Imax/Bmax,	(self-field), kA	Issl(Bmax,T0)
		kA/T	(seii-field), KA	, kA
HFDM04 (coil #01)	4.5	7.2 / 6	12.6	6.5 - 16.4
HFDM05 (coil #02)	4.5	8.2 / 6.6	12.5	? - 15.4

No formal cleaning process was used on the cable before insulating. Before insulating, the cable was heat-treated at 200 ° C for 30 min to reduce residual stresses in the cable. These stresses come from a combination of the strand and cable manufacturing processes

3.0 COIL FABRICATION

3.1 Cable and Wedge Insulation

The original cable cross-section design for HFDM05 (coil HFDDH-002) included a keystone angle of 1.3 degrees, with mid-thickness of 1.240 mm. All coil parts (straight section and ends) were manufactured to accept this cross section. This specification was subsequently changed, and the actual cable supplied had a keystone angle of .972 degrees, with a mid-thickness of 1.258 mm, but coil parts as originally designed were used. The cable and wedge insulation was adjusted to help compensate for these differences. The adjustment was originally made for magnet HFDM04. The system and the reasons for choosing it is described in detail in Section 3.1 of the production report for that magnet (TD-05-023). The amount of cable and wedge insulation used in HFDM05 is identical to that used for HFDM04, and consists of one layer of 5 mil x ½ inch wide dry ceramic tape, with a 30% overlap.

After winding but before curing, the insulated cable was painted with CTD-1008 binder.

3.2 Coil Winding and Curing:

End part material was phosphor bronze. Parts were machined to fit the coil in the final, compressed state. In order to allow the parts to fit onto the uncompressed coil during winding, they were reworked by hand from the original design. This resulted in spaces between coil end turns and end parts after curing, which were filled with a mixture of ground ceramic tape and CTD-1008 binder.

Also, a layer of 2 mil thick mica was placed between each wedge surface and the insulation. The mica is used so that the cable does not stick azimuthally to the wedges. It is believed that, during excitation, if the wedges are bonded to the turns, the epoxy can crack between the wedges and turn, causing possible quenches. An identical mica sheet is also placed over the pole piece on the inner coil, along the straight section, from back of key to back of key, for the same reason.

Curing is done in a closed cavity mold manufactured to the nominal coil size. Curing is done at 150 degrees C for 1/2 hour. A 5 mil azimuthal shim made of kapton, placed on the sizing bar, and no radial shims, were used during curing. The coil is therefore cured to a size which is 5 mils smaller than the nominal size per side.

After curing the inner coil, inter-layer insulation was installed on the outside perimeter. Inter-layer insulation consisted of 3 layers of 5 mil thick ceramic cloth. The outer coil was then wound and cured at 150C. The inner coil is consequently cured twice.

The hydraulic pressure used to close the press to the mold cavity size was taken during curing. These measurements indicated that the azimuthal pressure on the coil needed to close the mold was about 35 MPa.

3.3 Coil Mechanical Measurements:

Coils are usually measured after curing, but before reaction, at various pressures to determine the shim size of the cavity in the reaction fixture. These measurements were not taken for coil HFDDH002, because the tooling was not available.

However, the hydraulic pressure used to close the press to the mold cavity size was taken during curing. These measurements indicated that the azimuthal pressure on the coil needed to close the mold was about 35 MPa, the same as for the previous coils. The same shim (zero) was therefore used in the reaction cavity. The coil was therefore reacted with the cavity at the nominal size. Based on measurements of previous coils, (see section 3.3 of HFDM03 production report), coil HFDDH-01 was smaller than nominal azimuthal size at 3 MPa, therefore subjected to very low pressure in the fixture before reaction. During the reaction process, the coil is expected to grow in size to fill the reaction mold. Very low pressure is used to avoid tin leaks during reaction.

3.4 Coil Electrical Measurements:

Electrical measurements (L, Q and R) were taken on both the coil before placing into the reaction fixture. The data is shown in Table 3.4.1. The values match the theoretical estimates, which indicate that the coil is free of turn-to-turn shorts. The inductance, L and Q was measured at 1 kHz and at 20KHz. Resistance was measured using four-wire technique at 0.1 A. Measurements were done on a wooden table with no mandrel.

Table 3.4.1 : Electrical	l measurements on th	e cured ha	elf-coil
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	Resistance mΩ	Inductance µH @ 20 Hz	Inductance µH @ 1KHz	Q @ 20 Hz	Q @ 1KHz
HFDDH002	119.8	609.62	532.57	.62	6.6

3.5 Ground Wrap System:

Inter-coil insulation consists of 3 layers of 5 mil (125um) ceramic sheet placed radially between inner and outer coil. Ground wrap consists of 3 layers of 5 mil (125um) ceramic sheet placed radially between outer coil and spacers. A quench protection (strip) heater, consisting of 2 stainless strips bonded to a 4 mil piece of kapton, is placed between the impregnated coil and the first sheet from the outer coil surface. The strip heater is inserted between the first and second layer of ground wrap after the coil is reacted but before it is impregnated.

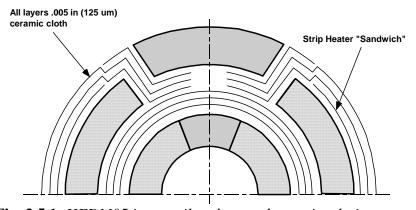


Fig. 3.5.1: HFDM05 inter-coil and ground wrap insulation system

The layers are "preformed" to the proper shape by painting with CTD-1008 and baking at 130C for 4 hours while wrapped onto a mandrel, which defines their shape. All layers are installed before the coils are reacted.

In fact, although the design calls for 15 mils of thickness for both the inter-layer and ground insulation, the sheets of "5 mil" being used measure about 6-7 mils each after curing.

4.0 COIL REACTION

4.1 Reaction Cycle

The half-coil was placed into an individual reaction fixture. The reaction fixture was installed into a retort as shown in Figure 4.1.1.



Figure 4.1.1: Coil HFDDH-002 in retort with witness samples

The reaction cycle of the coil HFDDH002 is described in detail below:

The reaction cycle of the 2nd RRP, .7mm strand coil (#HFDDH02) was begun at 2:00 PM on March 4, 2005. Oven used is the L & L oven in IB3. It is scheduled to be used in mirror magnet HFDM05.

The oven control is split into six "banks" of resistive coils. Each of these banks can be adjusted up or down individually, from settings of 0 to 999, controlling the local variations in the oven. The banks are adjusted, as they were on the last coil (HFDDH01, used in HFDM04) and on recent heat treatment experiments, as shown in Table 4.1.1.

Top sides	800
Bottom sides	999
Top door	700
Bottom door	800
Top back	950
Rottom back	950

Table 4.1.1. Heater Bank Settings

Length of steady state steps (called soak steps) are also extended to compensate for the lag time for the retort to reach the temperature of the programmed cycle, as was done on the HFDDH01 and recent tests.

Based on previous oven tests, the lag time is 20 hours at 210 degrees, 12 hours at 400 degrees, and 6 hours at 650 degrees. The exact cycle (as programmed) for HFDDH02 is shown in Table 4.1.2:

Table 4.1.2. Reaction cycle for HFDDH02

Beginning set point: 20C			Time (hr:min)	
Step 1	Ramp	from 20C to 215C at 25C/hr.	8:00	
Step 2	Soak	215C	90:00	
Step 3	Ramp	from 215C to 216C at 1C/hr.	1:00	
Step 4	Soak	216C	29:00	
Step 5	Ramp	from 216C to 400C at 50C/hr.	3:36	
Step 6	Soak	400C	60:00	
Step 7	Ramp	from 400C to 650C at 75C/hr.	3:28	
Step 8	Soak	650C	56:00	
Step 9	Ramp	From 650C to 20C	48:00	
Step 10	Soak	20C	till removed	

Temperatures are also adjusted to compensate for offsets between programmed and actual temperatures. Based on past thermocouple measurements, the actual values at the temperatures programmed above were expected to be:

- At programmed temperature of 215C: Actual temperature 208C-211C.
- At programmed temperature of 400C: Actual temperature is 392C-395C.
- At programmed temperature of 650C: Actual temperature is 639C-646C.

The temperatures have been slightly modified from that used on the previous coil HFDDH01. The cycle used for HFDDH01 is shown in Table 4.1.3.

Table 4.1.3. Reaction cycle for HFDDH01

Beginning set point: 20C			Time (hr:min)
Step 1	Ramp	from 20C to 220C at 25C/hr.	8:00
Step 2	Soak	220C	90:00
Step 3	Ramp	from 220C to 221C at 1C/hr.	1:00
Step 4	Soak	221C	30:00
Step 5	Ramp	from 221C to 400C at 50C/hr.	3:36
Step 6	Soak	400C	60:00
Step 7	Ramp	from 400C to 660C at 75C/hr.	3:28
Step 8	Soak	660C	56:00
Step 9	Ramp	From 660C to 20C	48:00
Step 10	Soak	20C	till removed

Figure 4.1.2 shows the positions of the thermocouples used on recent cycles.

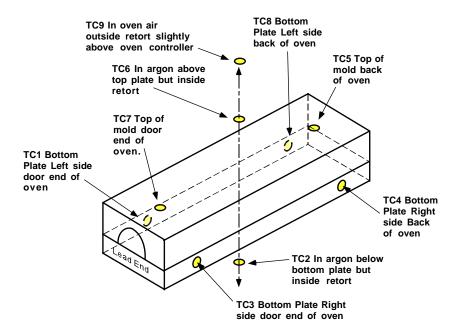


Figure 4.1.2. *Thermocouples on Reaction Fixture*

Unfortunately, only three thermocouples are currently functional. They are placed within the retort at positions TC7, TC5, and TC4 shown in Figure 4.1.2. There are still three thermocouples outside the retort, TC9 and the two that are integral to the oven.

Actual cycle for coil HFDDH002, as read by thermocouples, is shown in Figures 4.1.3 through 4.1.9. The horizontal axis in the figures represents the sampling rate for the data of 2 minute intervals.

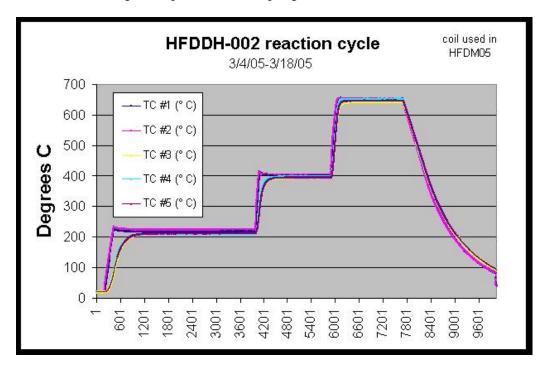


Figure 4.1.3: Complete Reaction cycle of HFDDH002

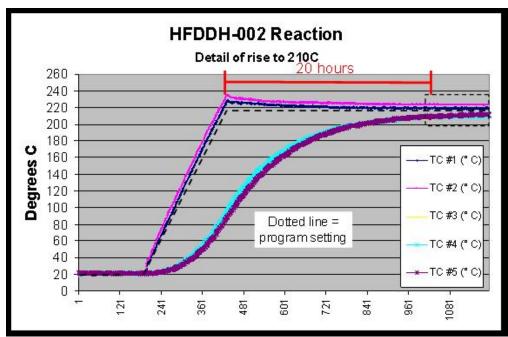


Figure 4.1.4: Detail of rise to 210C

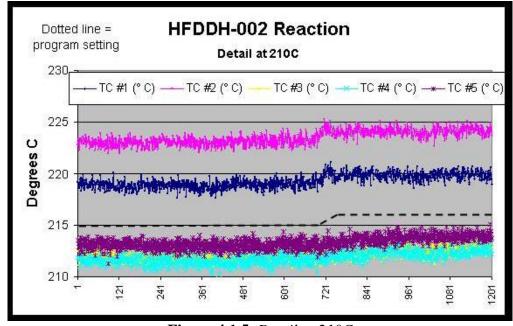


Figure 4.1.5: *Detail at 210C*

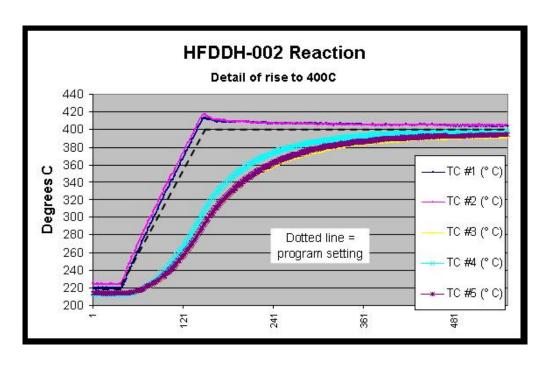


Figure 4.1.6: Detail of rise from 210C to 400C

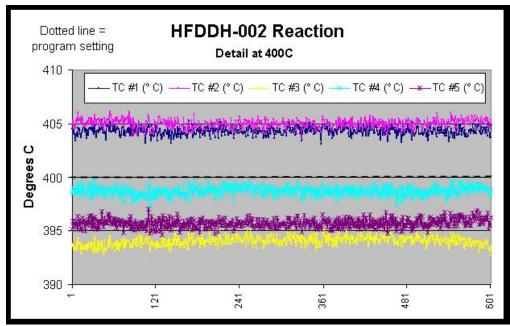


Figure 4.1.7: *Detail at 400C*

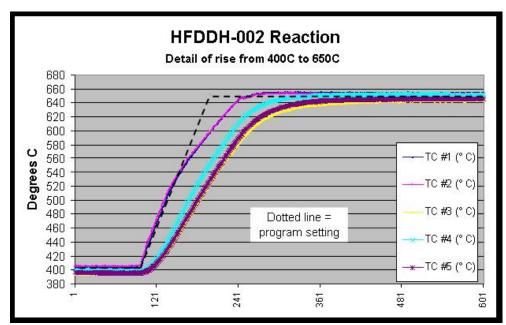


Figure 4.1.8: Detail of ramp from 400C to 650C

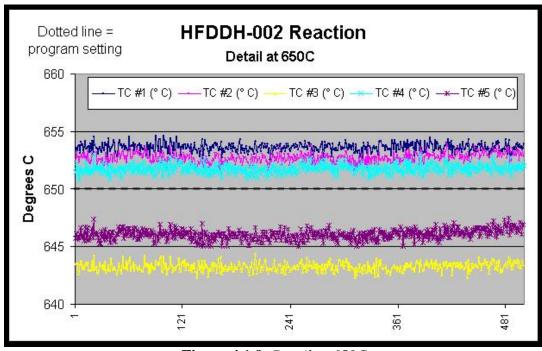


Figure 4.1.9: *Detail at 650C*

4.2 Voltage Taps and Spot Heaters

Voltage taps were mounted to the coils as shown in Figure 4.2.1. There were no voltage taps on the return end. HFDM05 did not contain spot heaters. Figure 4.2.1 shows coils as viewed from the inside (looking at concave surface).

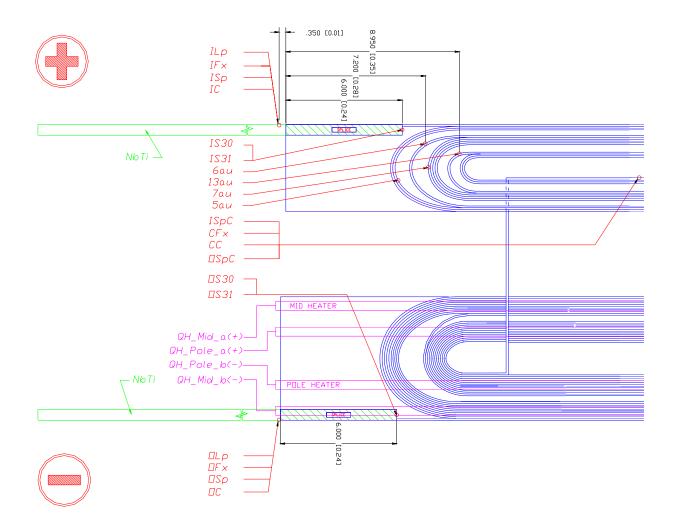


Figure 4.2.1: *Voltage Tap Layout.*

4.3 Strip Heaters:

Quench protection (strip) heaters were placed radially outside the outer coils, between the first and second layers of ground wrap, radially as shown in Figure 3.5.1 and azimuthally as shown in Figure 4.2.1. Each strip heater, consists of (2) 3/8 inch wide x 25 micron thick stainless strips bonded to a 4 mil piece of kapton. Each quadrant contained one assembly, with each strip placed approximately over the center of a current block. Strip heaters are inserted by hand, after reaction but before impregnation. The heater-wiring schematic is shown in Fig. 4.3.1.

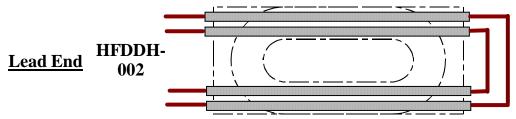


Figure 4.3.1: Quench Protection heater wiring schematic.

4.4 Parting plane Splices:

The midplane splices were done in the same manner as all Nb₃Sn dipoles have been done since HFDA-04, so that the splice joint is well supported, and the Nb₃Sn cable cannot be subjected to bending strain. This splice configuration is explained in detail in the HFDA-04 production report, TD-02-025. Splicing was done after reaction with the coil still housed in the same tooling used for reaction. Solder was 70%/30% lead/tin with Kester 44 flux. Solder is heated to a temperature of approximately 230C.

5.0 **EPOXY IMPREGNATION**

Coil HFDDH-002 was impregnated after splicing in the same fixture that was used for reaction. Figure 5.0.1 shows an identical coil, HFDDH-001, enclosed in the tooling and being prepared for impregnation. Equivalent pictures of HFDDH002 are not available.





Fig. 5.0.1: Coil in reaction-impregnation tooling being prepared for impregnation (HFDDH-001 shown)

5.1 Impregnation Cycle:

Coils were impregnated with CTD101K epoxy. The impregnation fixture was placed in a large oven, heated to 60C and evacuated to 75 microns. The container of epoxy was heated to 55C and evacuated to about 115C. The epoxy flow rate into the coil was .04cc/sec (.5cm/sec linear flow in a tube of 3.2 mm inside diameter). Epoxy was flowed at this rate for 1 hour 40 minutes, the time it takes to fill about half the coil. Flow was then stopped for 2 hours to allow the epoxy to fill all spaces. Flow was then resumed. The coil took 2 more hours to fill, after which flow was continued for another 1 hour 15 minutes. Total time for the impregnation process was approximately 7 hours. After impregnation, the fixture was placed into an oven and cured at 125C for 21 hours.



Figure 5.1.2 *Coil assembly after impregnation (HFDDH001 shown).*

5.2 Mechanical Measurements:

The thickness, width and flatness of the coil were measured after impregnation (in the free state), as shown if Figures 5.2.1. and 5.2.2. Plots of these three measurements for HFDDH-002 are shown in Figures 5.2.3, 5.2.4 and 5.2.5. In the thickness and width measurement plots, yellow dots indicate points in the straight section, not covered by end parts.

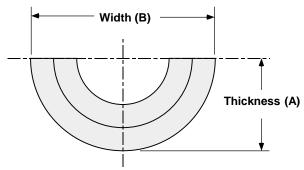


Figure 5.2.1 Width and Thickness Measurements

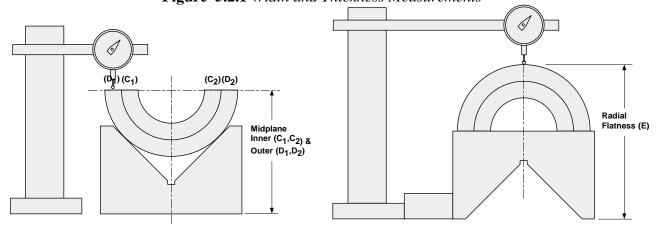
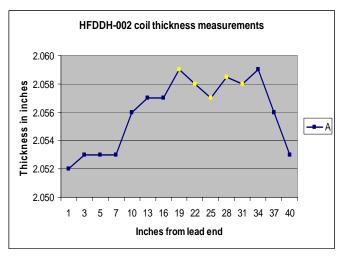


Figure 5.2.2 Flatness Measurement Positions



HFDDH-002 coil width measurements

4.104
4.103
4.102
4.101
4.100
4.099
4.098
4.097
1 3 5 7 10 13 16 19 22 25 28 31 34 37 40
Inches from lead end

Figure 5.2.3 Coil Thickness Measurements

Figure 5.2.4 Coil Width Measurements

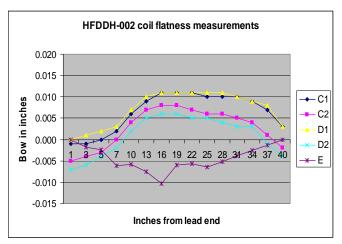


Figure 5.2.5 Coil Flatness Measurements

5.3 Calculation of Coil Radial Shim:

Radial shims may be placed around the outside of the coils, to compensate for differences between coil radial actual and design size. These shims are calculated based on the measurements taken in section 5.2.

After extraction from the impregnation mold, the coil deflects. The shape it takes is modeled as half of an ellipse in 2D cross-section. The coil outer radius is re-calculated based on the assumption that the perimeter the ellipse and circle for the outside surface of the outer coil are equal. The ellipse perimeter can be computed using the rapidly converging Gauss-Kummer series as follow:

$$P = \pi(a+b) \sum_{n=0}^{\infty} {1 \over 2 \choose n}^2 h^n = \pi(a+b) (1 + \frac{1}{4}h + \frac{1}{64}h^2 + \frac{1}{256}h^3 + \ldots)$$

where
$$h \equiv \left(\frac{a-b}{a+b}\right)^2$$
.

Results for coil HFDDH002 are shown in Table 5.3.1.

Table 5.3.1 *Coil Radial Shim Calculations*

Coil	a=A	b=B/2	$h=((a-b)/(a+b))^2$	Pe(n=0)	Pe(n=1)	Pe(n=2)	Pe(n=3)	Rcycle	Radius	Coil design
								= Pe/pi/2	design	w/respect
										to actual
										radial size
002	2.058	2.0505	3.33e-06	12.90723	12.90724	12.90724	12.90724	2.054252	2.052	002252

The results show that the impregnated coil outside diameter is larger than the design size by ~ 4.5 mil (114 microns). Note: The measurements in section 5.2 were taken without the 2 mil kapton shim described in the beginning of section 6.3.

5.4 Electrical Measurements:

Coil Electrical Measurements were taken after impregnation, and are shown in Table 5.4.1. Resistance measurements were taken at .1 amp. Inductance and Q were taken both at 20 Hz and 1KHz.

Table 5.4.1: *Electrical measurements on the impregnated half-coil.*

	Resistance mΩ		Inductance µH @ 1KHz	Q @ 20 Hz	Q @ 1KHz
HFDDH-002	165.7	615.69	498.91	.46	4.55

6.0 YOKING

6.1 Magnet Structure

General structure of HFDM05 is shown pictorially in Figure 6.1.1. It has a horizontally split yoke. Aluminum-bronze spacers surround the coil inside the yoke, ending azimuthally at the coil parting plane, along the same plane as the yoke is split. The space which would normally be taken by the lower coil half is occupied by a solid steel "mirror". Stainless steel strips are placed between the mirror and coil parting plane as shown in Figure 6.1.1. The stainless strip can be shimmed to a size appropriate to the particular magnet being assembled. Preload is achieved by a combination of the aluminum yoke clamps and skin. The skin may be either welded or bolted, and is bolted in the case of HFDM05. There is a gap between yoke halves, which remains open at all stages of construction and testing, even during cool-down and powering.

By design, the coil preload and internal stresses of the components vary during construction, cool-down and operation, approximately as described below:

1) When the magnet is at room temperature, and the coil preload is zero, the yoke gap by design is open, while the gap between the stainless strips and coil is exactly zero. The spacers are not under any stress, either azimuthally or radially.

- 2) Pressure is applied by the press to the yoke halves, reducing the yoke gap and applying radial stress to the coils through the spacers. The spacers are loaded radially, but not azimuthally, because there is a large azimuthal gap between the spacers and the mirror. Azimuthal compressive (hoop) stress is therefore applied to the coils, as the coil parting plane is pressed against the stainless steel strips.
- 3) The yoke clamps are inserted and the press pressure is released, transferring the press pressure to tensile stress in the yoke clamps. The inside surfaces of the yoke clamps are now in contact with the yoke, and there is still a gap between the yoke halves.
- 4) The skin is bolted onto the yoke, applying preload to the coils, relieving some but not all of the stress from the yoke clamps. The skin is now in azimuthal tension, and the inside surfaces of the yoke clamps are still in contact with the yoke. Stress on the spacers and coil is unchanged from step 3.
- 5) During cooldown, all components shrink (at different rates). The yoke gap remains open, and the tensile stress in the skin and yoke clamps increase.
- 6) During excitation, Forces are applied radially outward by the coils at the parting plane. These forces are contained by the skin and the yoke clamps.

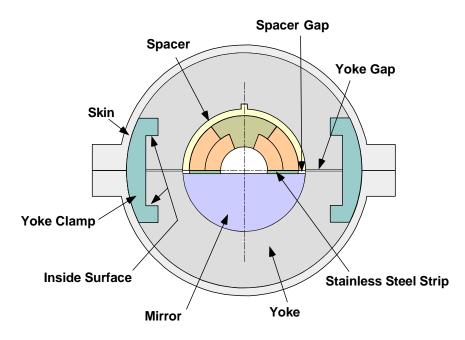


Figure 6.1.1 HFDM05 General Structure

6.2 Instrumentation

Both capacitance and traditional resistive beam strain gauges were used to measure coil azimuthal preload. Capacitance gauges (designated CG) and beam gauges (designated BG) were imbedded into the mirror at the midplane as shown in Figure 6.2.1. Gauges BG63 and BG64 measure preload at the inner and outer splices, respectively. BG61 and BG62 measure inner coil body preload. BG65, BG67, CG50 and CG51, measure outer coil body preload.

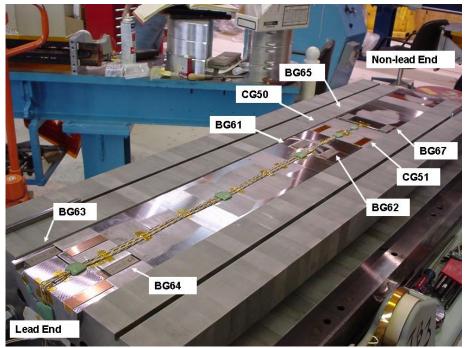


Figure 6.2.1 Midplane gauges in HFDM05

In addition to the midplane gauges, two capacitance gauges, CG62 and CG61, were placed at the outer pole in the body, at the same longitudinal position as gauges CG50 and CG51, with CG62 opposing CG50 and CG61 opposing CG51, as shown in Figure 6.2.2. To achieve this, the outer pole piece at this position was mold released before epoxy impregnation and removed afterwards, then replaced with a special outer pole piece modified to accept capacitance gauges. Resistive gauges, mounted into circumferential grooves on the aluminum bronze spacers, used on HFDA04, were not used in HFDM05.

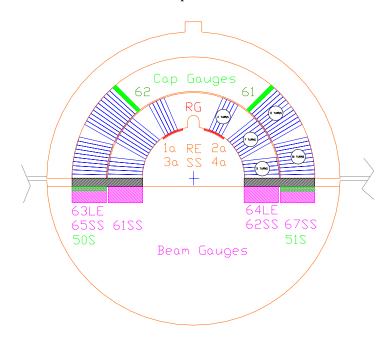


Figure 6.2.2. *General gauge layout in cross section center of magnet.*

Strain gauges were also mounted onto the inside surface of the coil, at the position s shown in Figure 6.2.3.

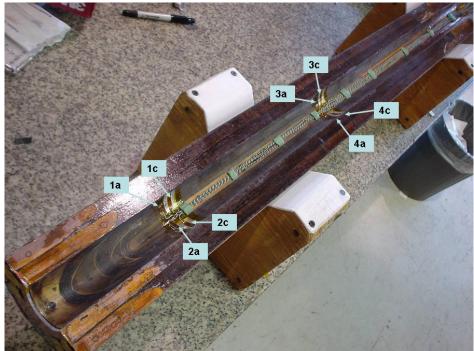


Figure 6.2.3: *Resistive gauges mounted to inside coil surface.*

6.3 Yoke Assembly

A sketch of the complete HFDM05 shim system is shown in Figure 6.3.1. The coil outside diameter, by design, should be at the nominal size to match the inside diameter of the spacers. Coil outside diameters and spacer inside diameters were measured (see sections 5.2 and 5.3). As a result of these measurements, a 3 mil kapton sheet was used as a radial shim between coils and spacers. The stainless steel strip at the mid-plane of the coil was shimmed with a 50-100 um tapered kapton shim as shown in Figure 6.3.1 to achieve an azimuthal interference of 5 mils (125 microns). Aluminum bronze spacers were then placed around the coil. No kapton layer was placed radially between the spacer and the coil near the midplane, as was done on HFDM04 to increase preload at the pole. The top yoke packs were then installed. The completed yoke assembly is shown in Figure 6.3.2. The yoke gap remains open only at room temperature. By design, it is closed at 4K.

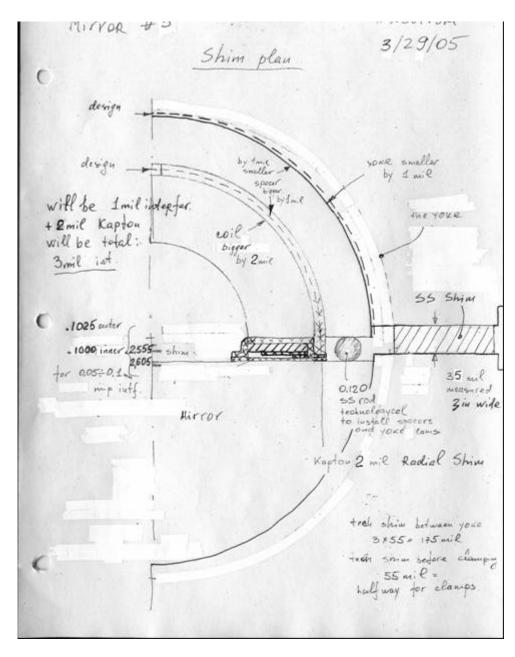


Figure 6.3.1 *HFDM05 shim system*

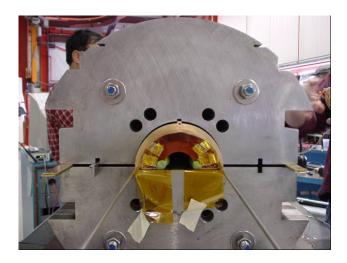




Figure 6.3.2 *Mirror in Yoke (HFDM04 shown)*

6.4 Pressing

Iron mirror blocks were placed in the lower yoke half. The coil was then installed onto the mirror as shown in Figure 6.2.3. After the upper yoke blocks were installed, the entire assembly was placed into the yoke press and compressed vertically. Once the nominal yoke gap was achieved, the press position was locked and the yoke clamps were inserted. After insertion of the yoke clamps all press pressure was released. Figure 6.4.1 shows the previous identical magnet, HFDM04, in the yoke press.



Figure 6.4.1 HFDM04 in Yoke Press.

Gauges were read during pressing and later assembly steps. Figure 6.4.2 shows outer coil capacitor guage readings through yoking and installation of skin. Figures 6.4.3 and 6.4.4 show readings of the resistive

beam gauges, at the lead end and straight section respectively. Figure 6.4.5 shows readings of the resistive gauges mounted to the coil inside radius during the same assembly steps. In these plots, the horizontal axis describes press pump psi during yoking (clamping). Main cylinder force is 180 lbs. per pump psi across the entire magnet.

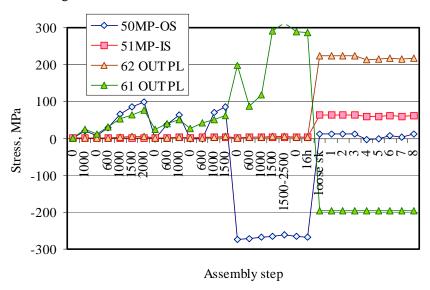


Figure 6.4.2 Capacitor gauge readings on Outer Coil.

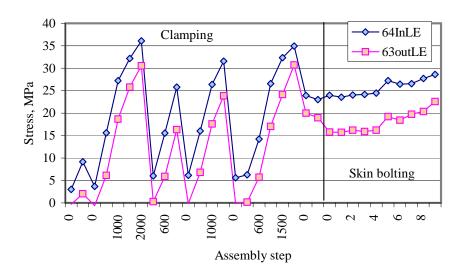


Figure 6.4.3 *Resistive beam gauge readings during Assembly at Lead End.*

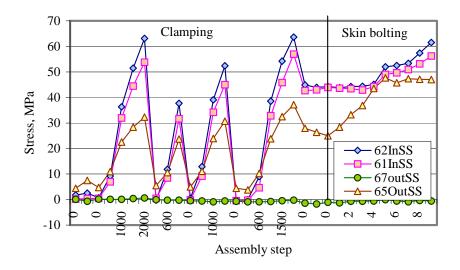


Figure 6.4.4 Resistive beam gauges during assembly in Straight Section

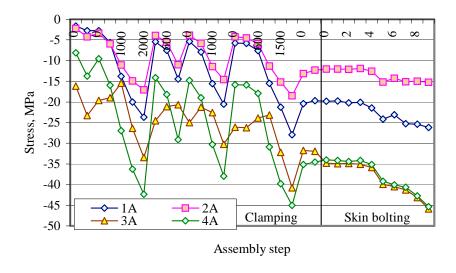


Figure 6.4.5 Resistive gauges on coil inside radius during Assembly.

6.5 Electrical Measurements

Coil Electrical Measurements were taken after pressing, and are shown in Table 6.5.1. Resistance measurements were taken at .1 amp. Inductance and Q were taken both at 20 Hz and 1KHz.

Table 6.5.1: *Electrical measurements on the yoked assembly.*

	Resistance mΩ		Inductance µH @ 1KHz	() (a) 7(1) H7	Q @ 1KHz
HFDDH-002	167.41	1226.6	394.38	.81	1.46

7.0 FINAL ASSEMBLY

7.1 Skin Installation

Skin halves were placed around the yoked assembly and bolted together. Bolting was done in several steps, while stress in the coil and end spacers was monitored. Stresses during this operation are shown in the previous section 6.4.

Resistive gauges were also installed onto the surface of the skin. Gauges were mounted near the longitudinal center of the skin, positioned to measure the azimuthal strain in the surface. They were mounted on both the upper and lower skins, at azimuthal positions of 30, 60 and 90 degrees from the yoke/skin gap, as shown in Figure 7.1.4. These gauges were also monitored during the bolting operation. Figure 7.1.5 shows the skin gauge readings during the bolting steps. Figure 7.1.6 shows the gap between skin bars after bolting, longitudinally across the magnet.

"Bar Gap" is the distance between top and bottom flanges on the bolt-on skin during skin installation, as shown in Figure 7.1.7.

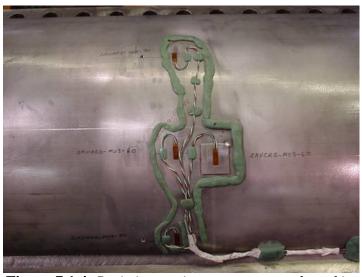


Figure 7.1.4: Resistive strain gauges mounted on skin.

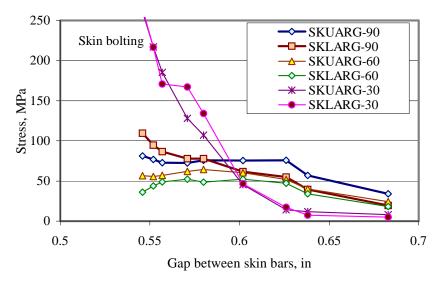


Figure 7.1.5 Stress in the skin during bolting read by skin gauges.

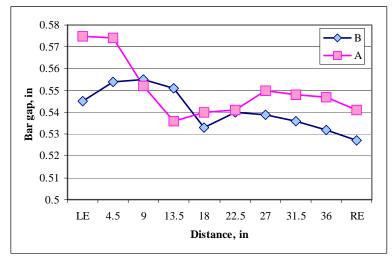


Figure 7.1.6 Gap between skin bars after skin bolting.



Figure 7.1.7 *Bar Gap.*

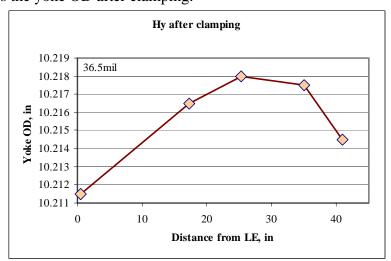


Figure 7.1.8 shows the yoke OD after clamping.

Figure 7.1.8 *Yoke OD after clamping.*

7.2 End Plate Installation

After the skin is installed, RTD's to measure the temperature during testing are installed. One RTD is installed in a hole on the spacer on each end.

An end plate is then bolted onto each end. Since this assembly was bolted, not welded, no twist measurements were taken.

The ends were not loaded longitudinally on HFDM05. Consequently no bullets were installed.

7.3 Splices

Since HFDM05 has only one coil pair, no splicing at the midplane was necessary. Leads were bent into a configuration similar to that used for a full dipole, and clamped to the end plate with G-10 blocks. The leads therefore exit the magnet at a position similar to that for a dipole, allowing easy hookup at the Magnet Test Facility. Clamping with the G-10 blocks also provides strain relief for the lead. Voltage taps were installed on the lead cables.

7.4 Connectors

Wires were terminated into 3 separate hypertronics connectors, one for quench characterization voltage taps, one for quench protection heaters, and one for resistive strain gauges (spacers and skin). A separate connector was used for RTD's (thermometers). Capacitance gauges are terminated using separate wires, with individual SMC female connectors.

7.5 Final Electrical Measurements

Final electrical measurements were performed on the magnet just before shipping to VMTF for testing. Initially, a coil-to-ground short was found. It was identified as a short between the outer coil lead as it exited the magnet and the inside surface of a bronze spacer, caused by a small amount of solder flash on the lead. The solder flash was removed, kapton was placed between the lead and the spacer, and a small

area of this spacer was relieved slightly. Subsequent electrical measurements showed the short to be eliminated. Table 7.5.1 summarizes the final measurements.

Table 7.5.1: *Electrical measurements on the total magnet.*

	Resistance	Inductance, μH		ce Inductance, µH Quality		Factor
	$m\Omega$	At 20 Hz	At 1 kHz	At 20 Hz	At 1 kHz	
Total Magnet	168.03	1227.7	395.42	.81	1.46	

Hi-Pot tests at 1000V were also performed on the final assembly to check current leakage between coil-to-ground, coil-to-heaters and heater-to-ground. The Table 7.5.2 shows these results.

Table 7.5.2: *Hi-Pot measurements on the yoked assembly.*

Test	Leakage @ 1000V
Coil to ground	.02 uA
Heaters to coil	.02 uA
Heaters to ground	.02 uA

Quench Protection (strip) heater resistance = 4.9 ohms per circuit, with each circuit consisting of two strips as shown in Figure 4.3.1.

8.0 **SUMMARY**

The sixth shell-type Nb₃Sn high field dipole mirror magnet, HFDM-05 was delivered to VMTF for testing on April 20, 2005.

HFDM05 had a 43mm bore diameter and a straight section approximately 1/2 meter long.

.7mm RRP strand manufactured by Oxford Industries was used. This is the second mirror to be produced at Fermilab with .7mm RRP strand, following HFDM04.